

Jet Propulsion Laboratory  
California Institute of Technology

# Mars Reconnaissance Orbiter Operations: Science Planning on NASA's Silent Workhorse



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Mars Reconnaissance Orbiter

Caltech Planetary Science Seminar

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URS \_\_\_\_\_

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**JPL**



**THE UNIVERSITY OF ARIZONA**



**LOCKHEED MARTIN**

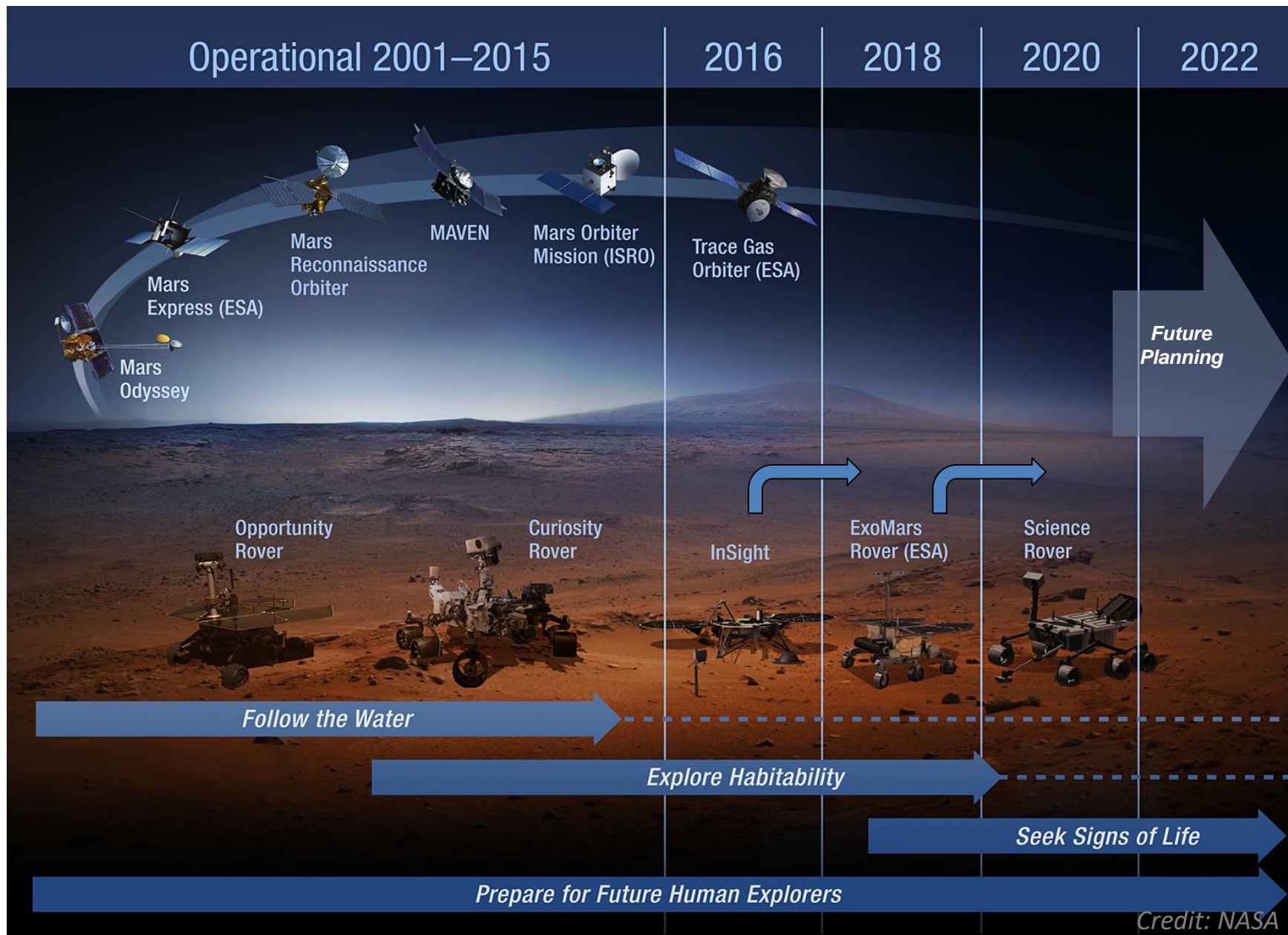


# Outline

## Science Planning on NASA's Silent Workhorse

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- Overview of MRO
- Overview of Science Planning and Challenges
- Science Planning on MRO
- Landing Site Selection as example of Science Planning

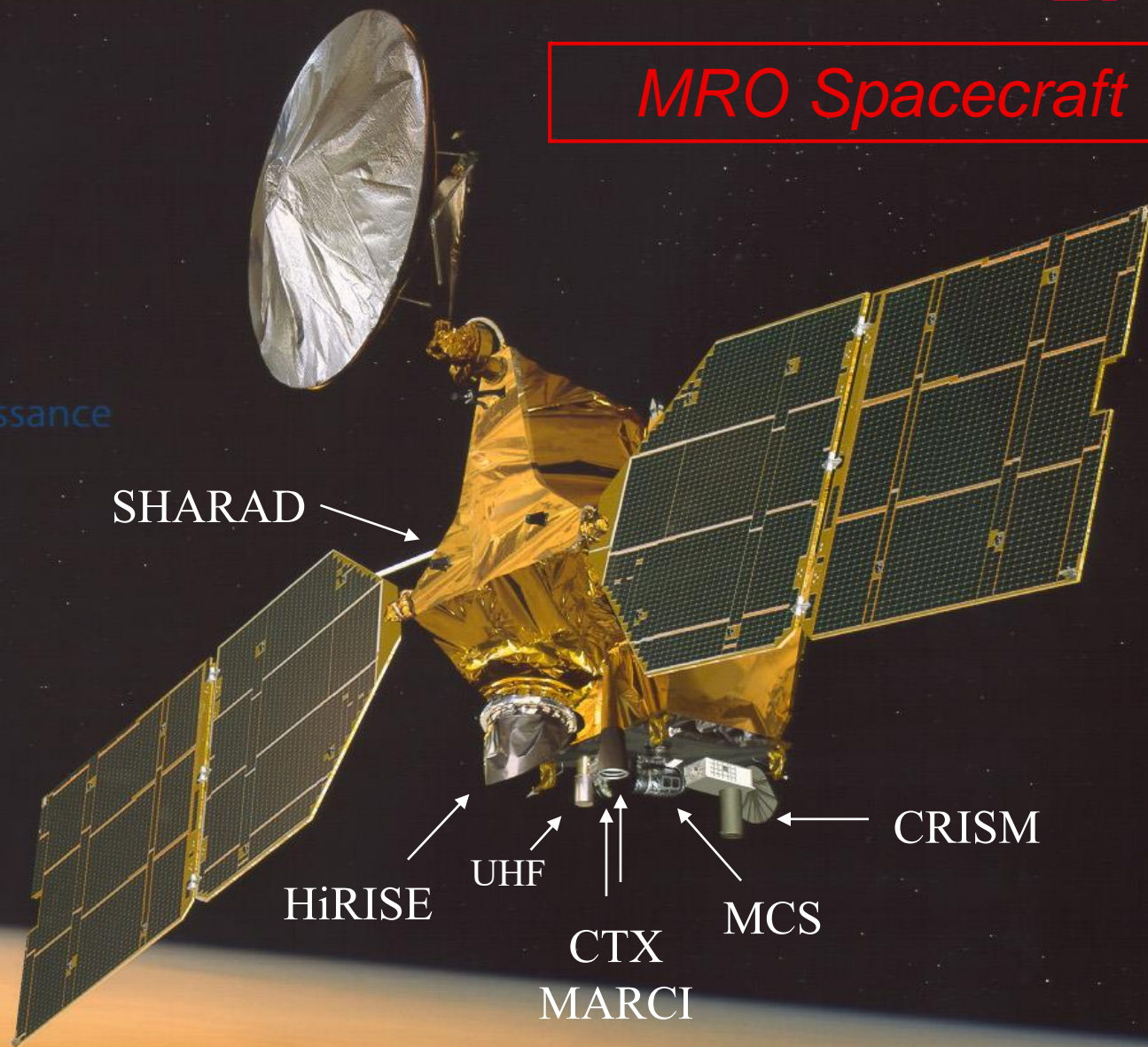






*MRO Spacecraft*

Mars  
Reconnaissance  
Orbiter



### ***Telecom:***

- X, Ka-Band & UHF
- 100 W X-Band TWTAs
- 3-m diameter High Gain Antenna

- *>300 Tb of Science Data Returned*
- *Retransmit capability increases reliability*

### ***Power:***

- Dual 50 A-Hr NH<sub>2</sub> Batteries
- 20 m<sup>2</sup> of GaAs 3J Solar Cells

## ***Supports Continuous Payload Operations***

### ***Propulsion:***

- Single-Tank Mono Prop Design
- 20 Yrs Consumables

## ***Fuel Not a Limit***

### ***Targeting:***

- Ephemeris-Based Targeting
- Time-Tagged Sequence Fully Supported
- *Precise targeting of almost any small target on Mars within a 2 week planning cycle*
- *Can roll off-nadir*

**2180 kg Launch Mass (Atlas V)  
On August 12, 2005**

**Currently in 4<sup>th</sup> Extended Mission**

**>50,000 orbits around Mars!**

***10 m radar antenna***

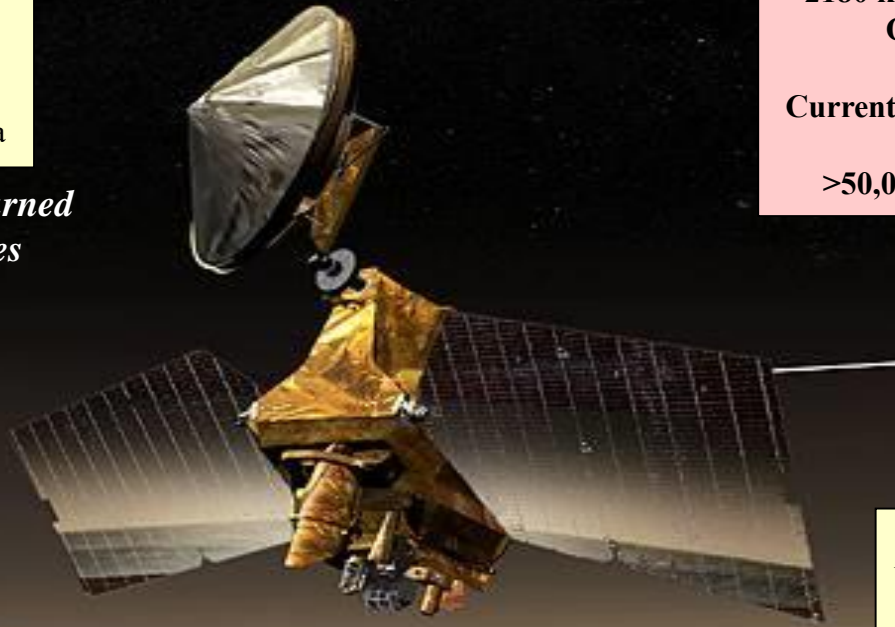
### ***Payload:***

- 6 Science Payloads
- 2 Eng Payload
- Electra Eng SS
- Simultaneous Operations
- Nested Targeting

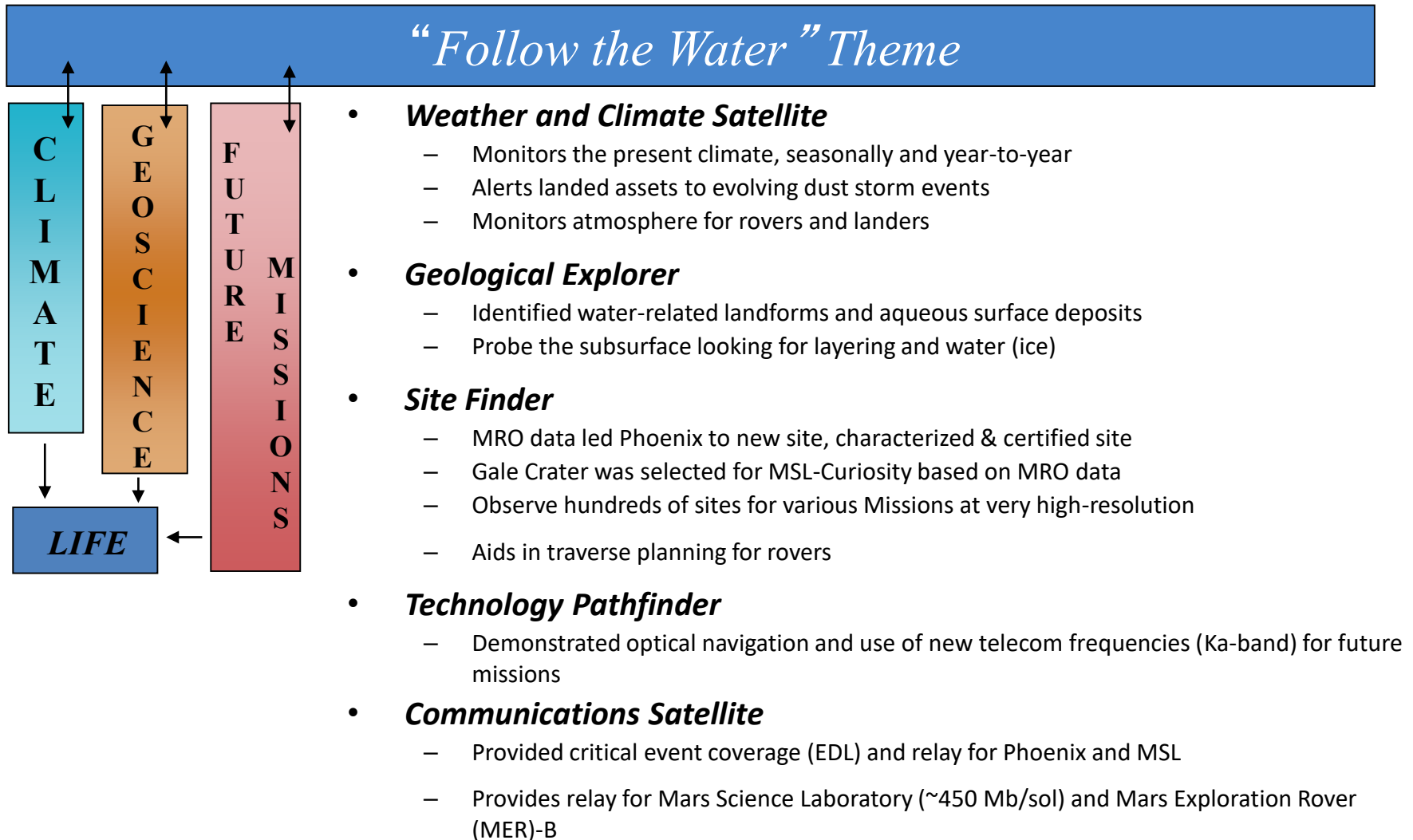
***All science payloads  
still operating after  
10+ years***

### ***Command/Data Handling:***

- RAD750 FPC
- 160 Gbit SSR
- 100 Mbps Science I/F



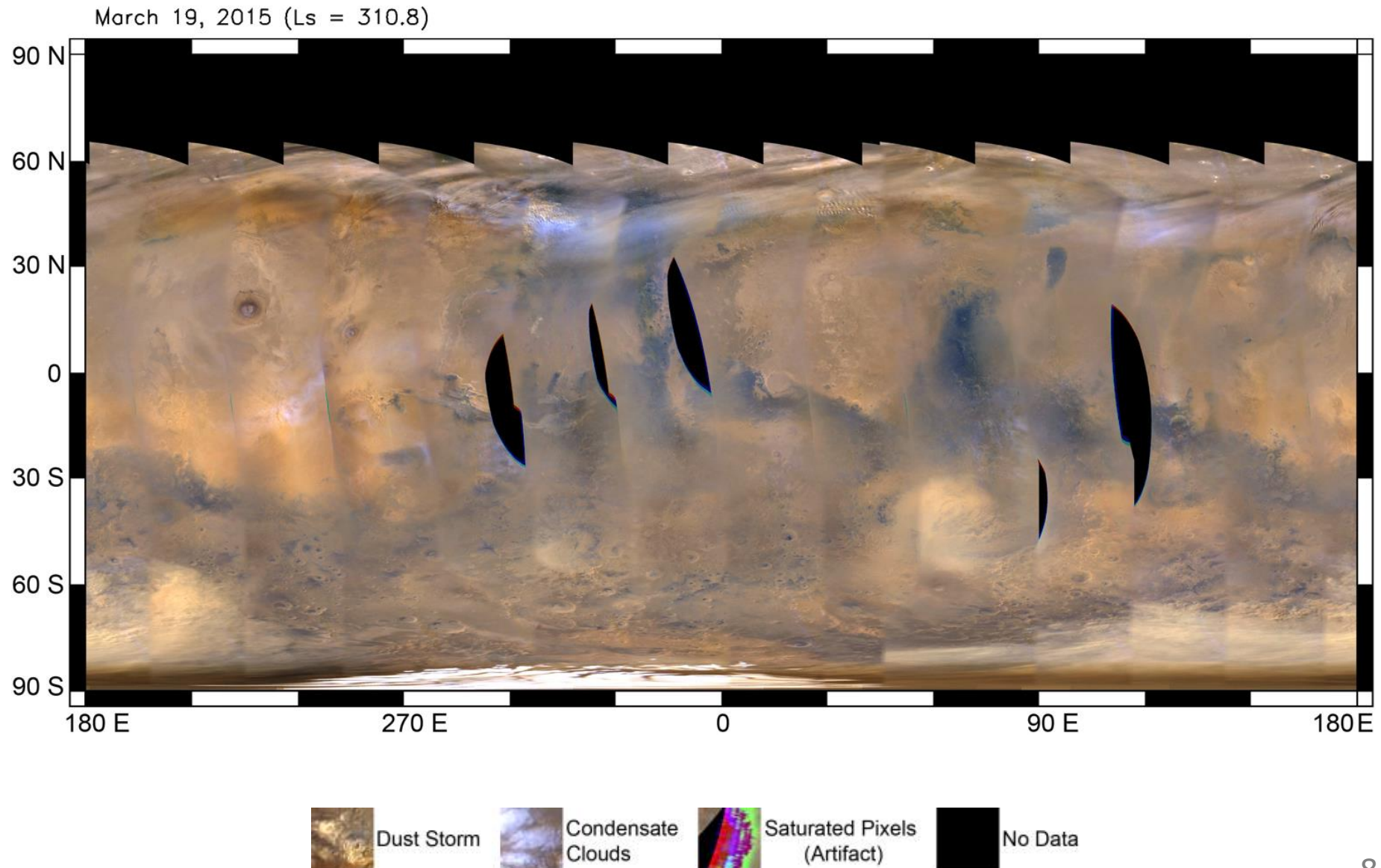
# MRO's Many Roles





# MRO's Many Roles

## MRO as a Weather and Climate Satellite

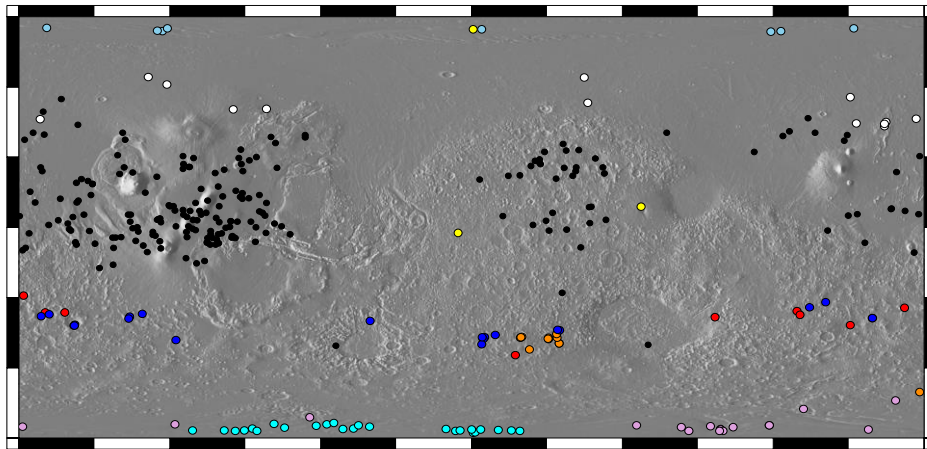


Slide adapted from Rich Zurek and Dan Johnston

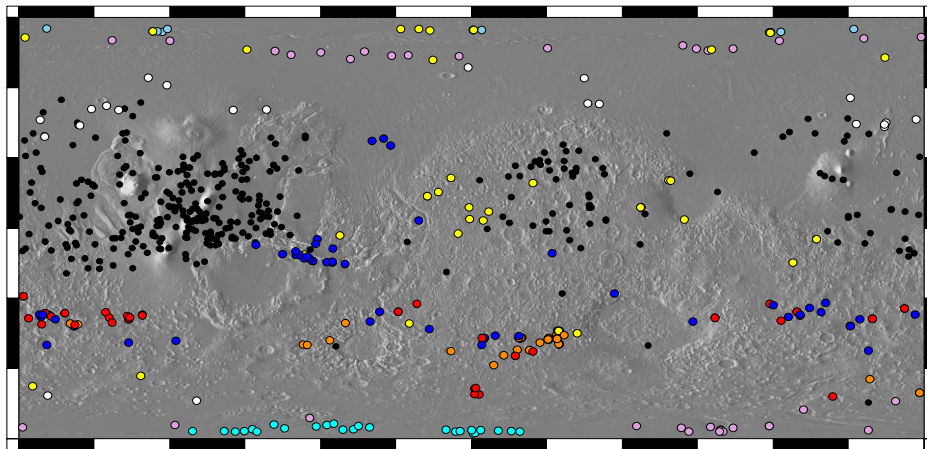


# MRO's Many Roles

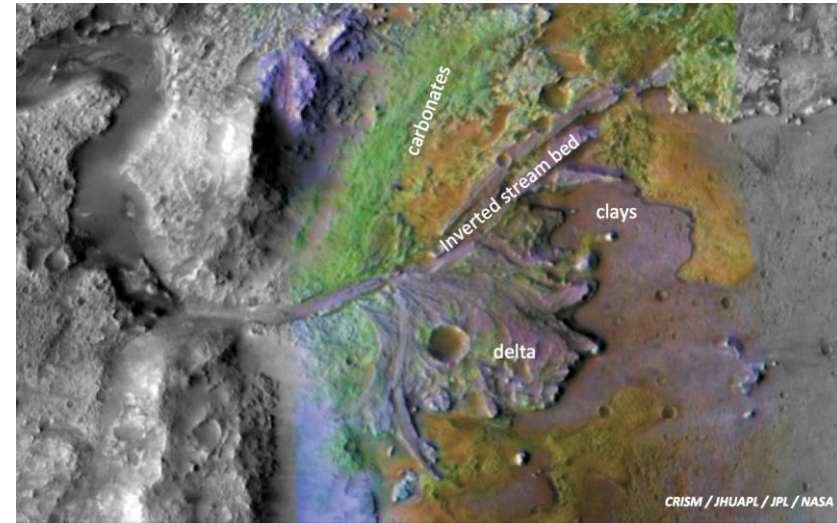
## MRO as a Geological Explorer



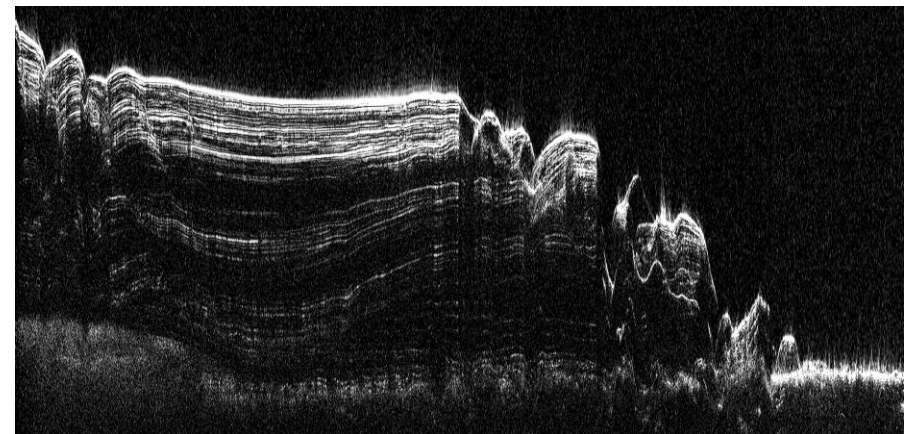
- |                         |                       |                    |
|-------------------------|-----------------------|--------------------|
| ● Defrosting Study Site | ● SPRC Study Site     | ● Polar Avalanches |
| ● New Impact Crater     | ● Ice-Exposing Crater | ● Active Dunes     |
| ● Active Gully          | ● Active Dune Gully   | ● RSL              |



Early 2012 (top) vs. Feb 2014 (bottom) *McEwen and Byrne*  
 Message: accelerating progress over time (HiRISE)



Jezero Crater: Morphology and Mineralogy Indicate Ancient Wet Past (CRISM)

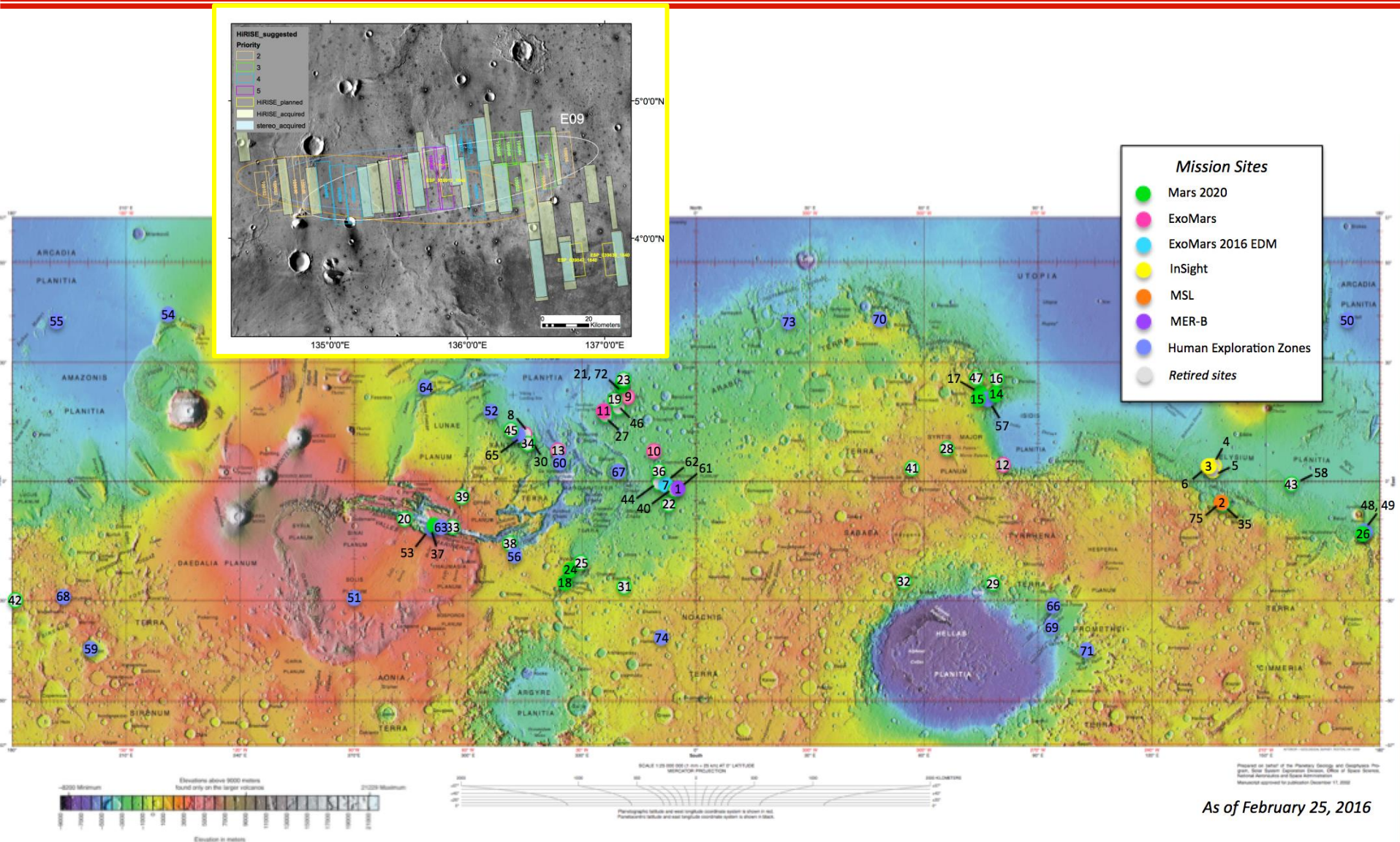


Layers of ice and dust cause radar reflections (SHARAD)  
 - Each layer records a different depositional environment  
 - Each layer represents a change in climate



# MRO's Many Roles

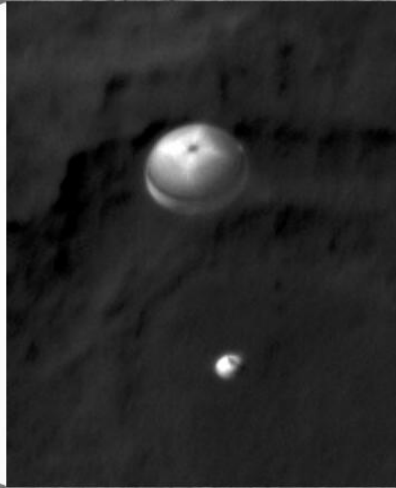
## MRO as a Site Finder



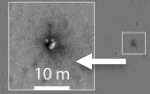
# MRO's Many Roles

MRO as a Communications Satellite

*MSL*

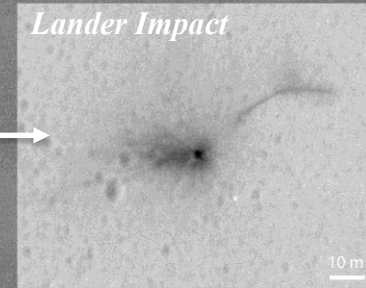


*EDM Heat Shield*



10 m

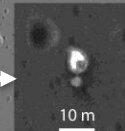
*Lander Impact*



10 m

*ExoMars EDM*

*Phoenix*



10 m

*EDM Backshell with Parachute*

100 m

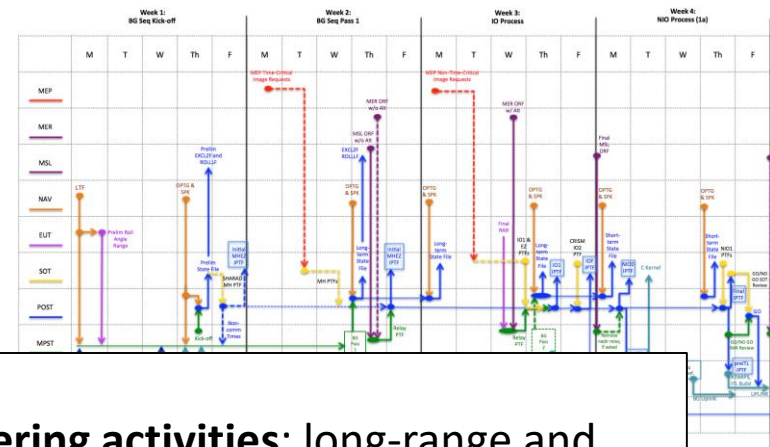
*Phoenix Lander*



*HiRISE / U. Arizona / JPL / NASA*  
*Slide adapted from Rich Zurek*



## Data Request → Acquisition



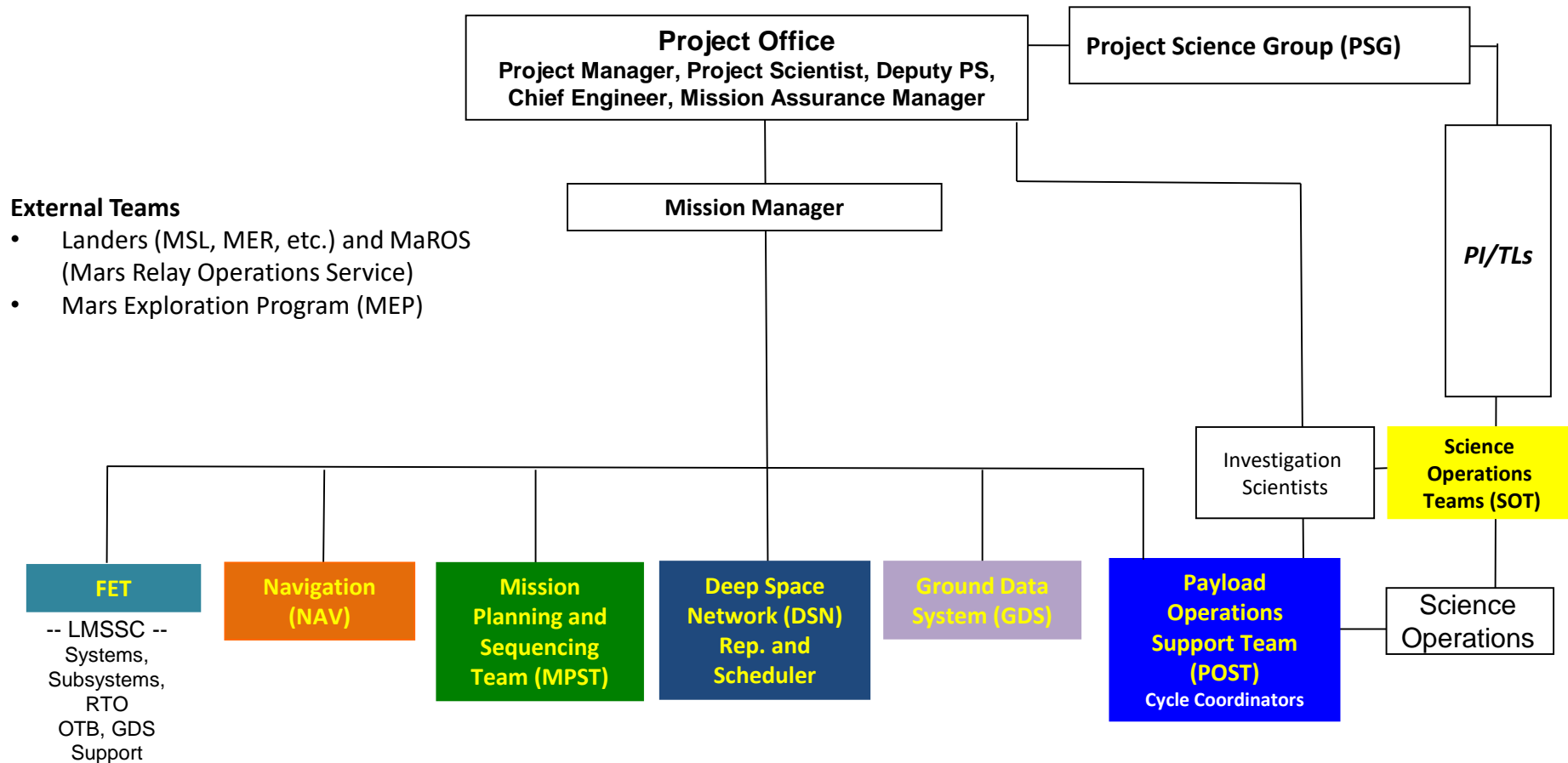
- 12



# MRO Science Planning

## MRO Operations Teams

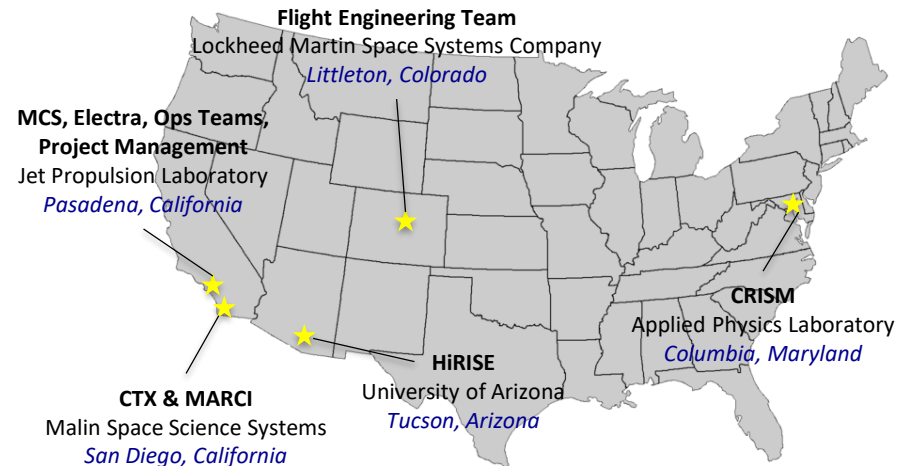
Science Planning is one team out of many on MRO



# MRO Science Planning

## Challenges

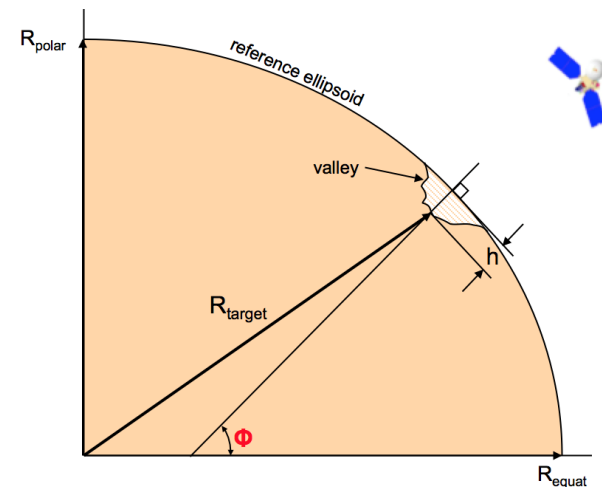
- Distributed operations teams
- Terminology of engineer vs. scientist
- Incompatible science motives
- Instrument constraints
- S/C constraints
- New requirements



# MRO Science Planning

End Goal: Integrated Target List (ITL)

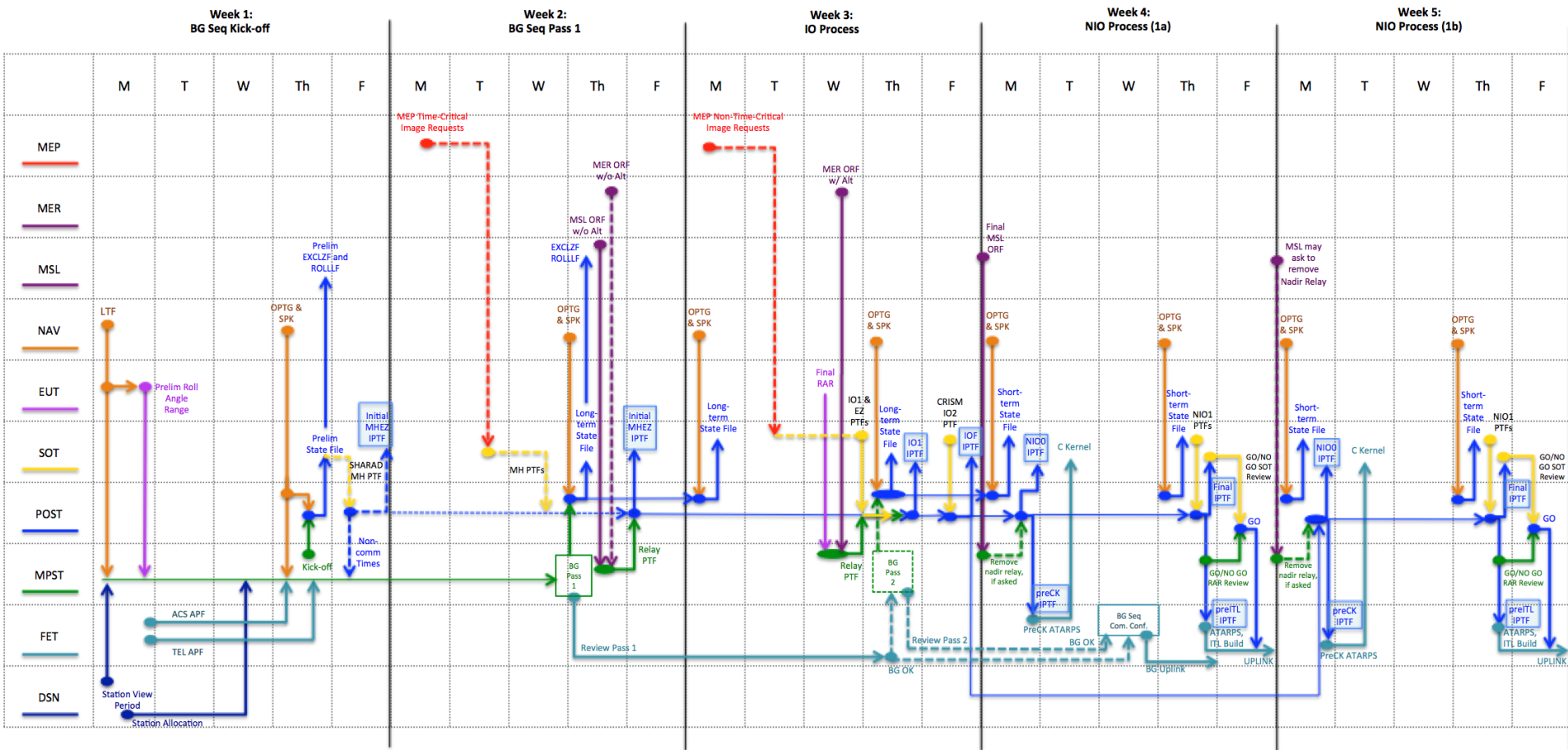
- List of targets for various instrument observations organized by S/C kickoff time
  - On-board software computes positions of the target
- Each line represents a target point on Mars
  - An estimated time of overflight (specified in SCLK seconds)
  - Location on planet
    - Areodetic latitude \*
    - East longitude \*
    - Height correction for terrain \*
  - Instrument parameters:
    - Setup time
    - Imaging time
    - File names, sequence names
- ITL targets will be rejected by the onboard software if they fail any of several constraint checks



\* As defined by a reference ellipsoid common to flight software and ground tools

# MRO Science Planning

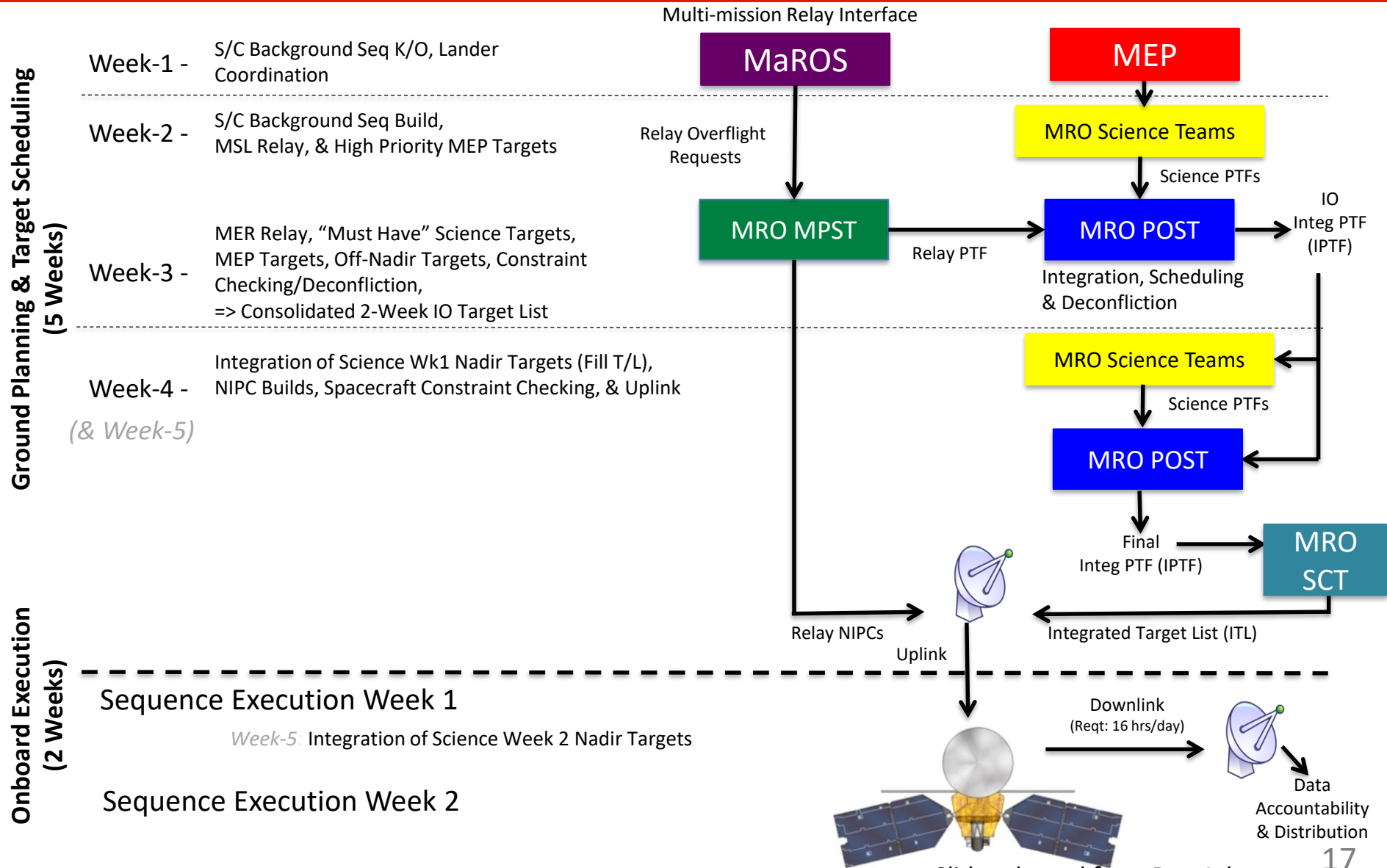
## Science Planning Process Schedule





# MRO Science Planning

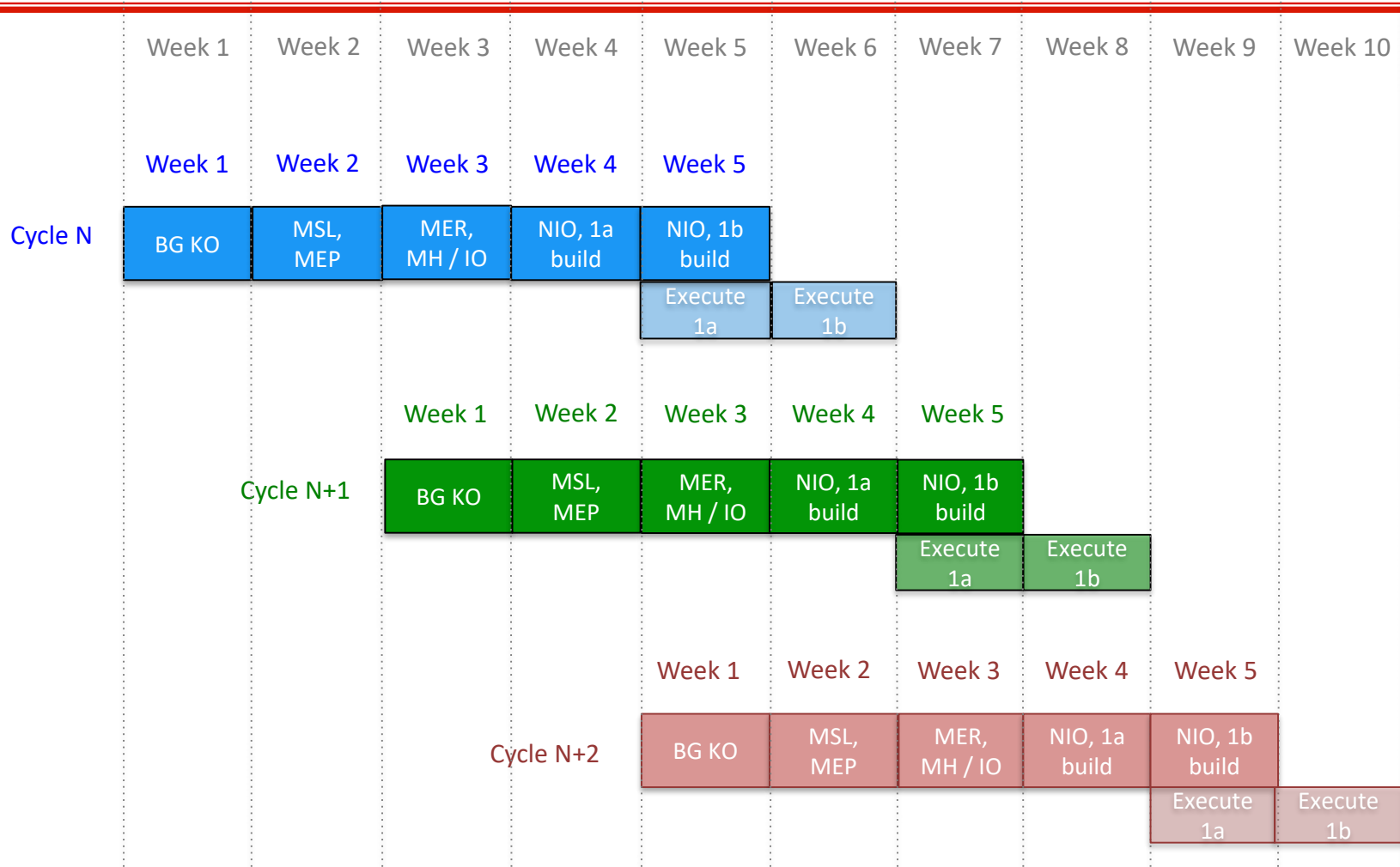
## Science Planning Process Overview



Slide adapted from Dan Johnston

# MRO Planning Schedule

## Science Planning Process Cycle Overlaps

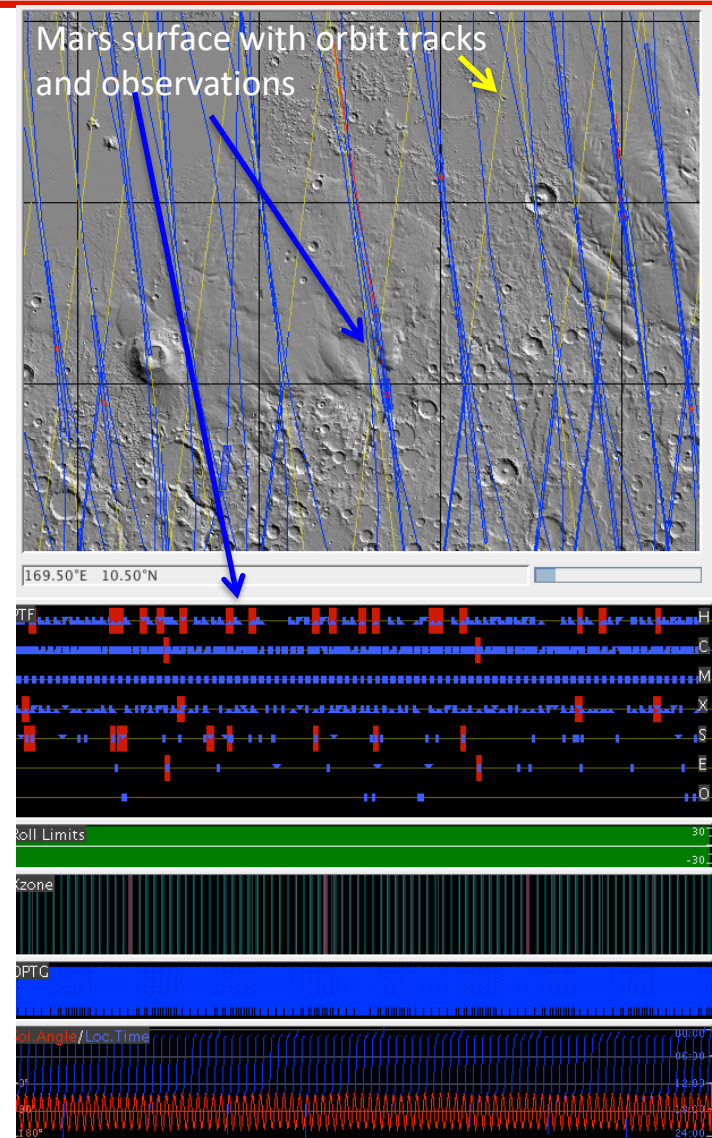


Reaction to any observations from N will not get into plan until N+2 at earliest

# MRO Science Planning

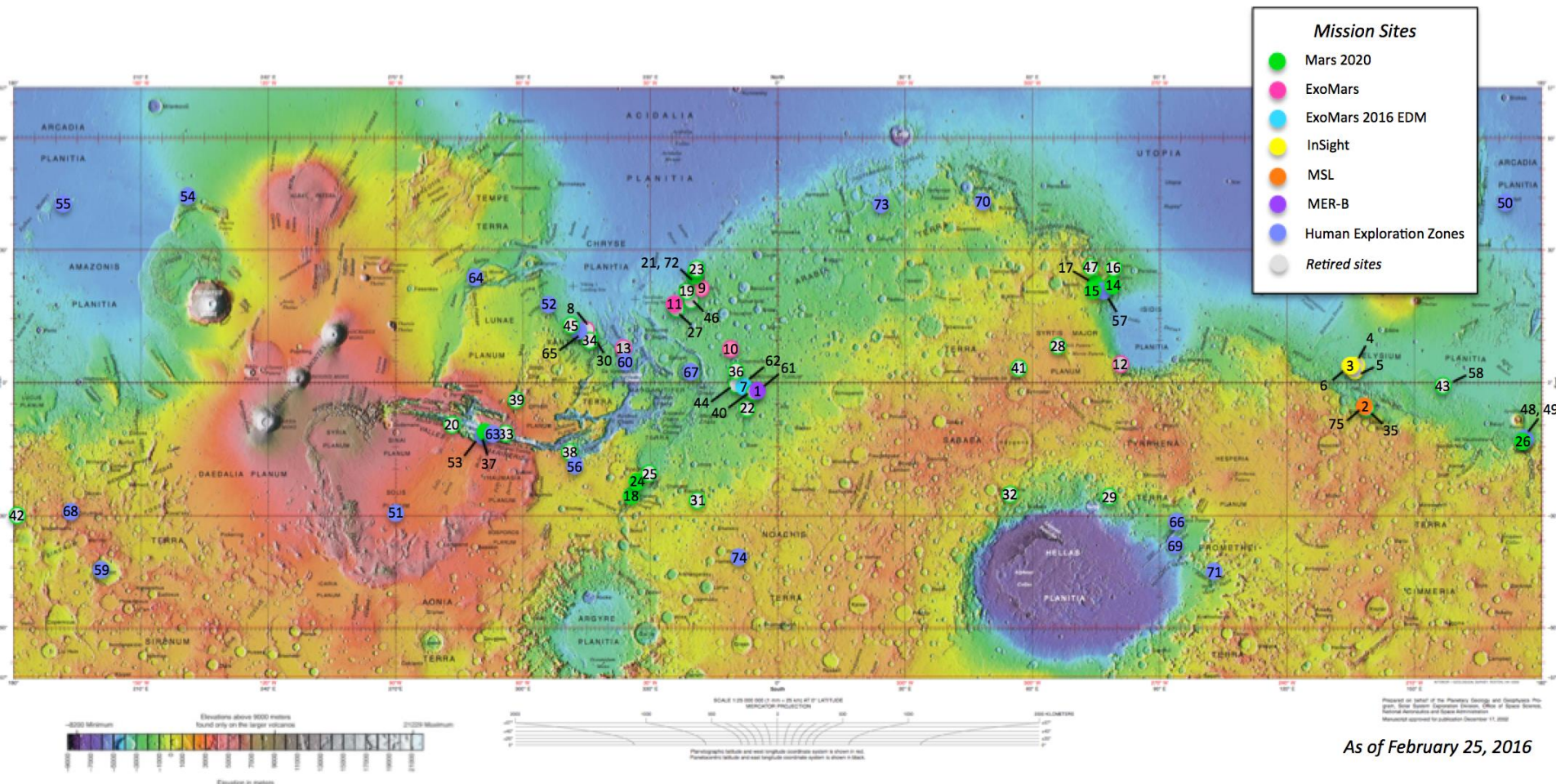
## Planning Software

- Use various scheduling software to aid in the science planning process
  - Visual representation of timeline via the Mars Targeting Tool, layer on top of JMARS (*Java Mission-planning and Analysis for Remote Sensing*)
  - Instrument teams tools and scripts
  - Several in-house scripts schedule observations
    - Based on priority of each team's own records
    - Schedule highest priority MHs first, followed by interactive stereo 2 observations by team, other interactive observations in round robin fashion, ride-alongs, nadir observations
  - Final check on target list performed by Systems at JPL or LMSCC (Denver), LMSCC performs check on S/C and gimbal motion



# Landing Site Selection

## Example of Science Planning on MRO



- MRO has supported or supports: PHX, MER, MSL, InSight, ExoMars, Mars 2020, Human Exploration Zones
- Over 800 mission targets on current campaign list (and 85% have been acquired)!

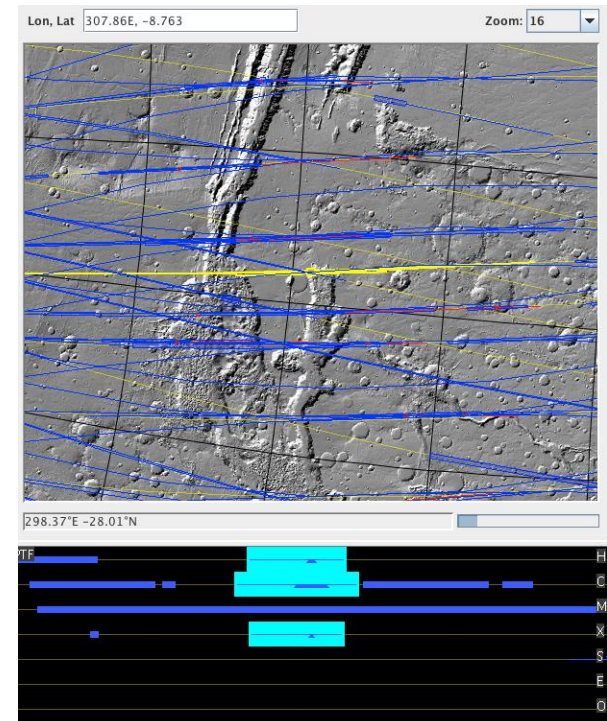


# Landing Site Selection

## Example of Science Planning on MRO

*Before the MRO Science Planners integrate the records, initial requests are fed into the process through the Instrument Teams*

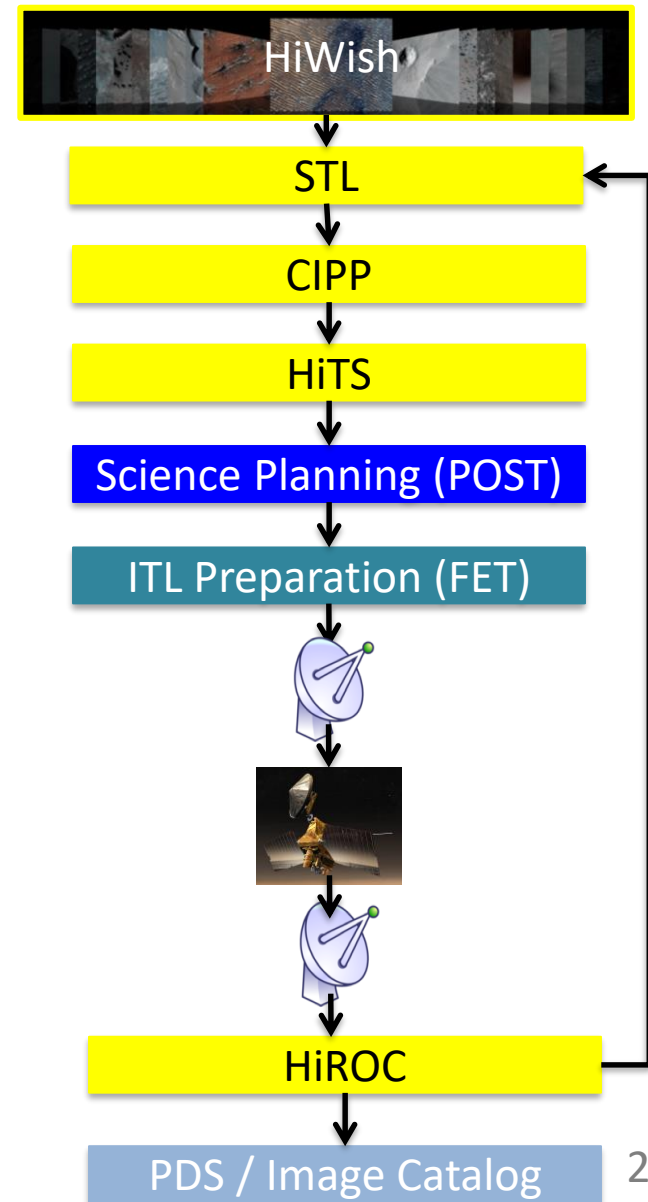
- Team/Individual selects a “driving” instrument
  - Determined based on the coverage requested
  - Center of target based on selected “driver”
- Other instruments can “ride-along”
  - Co-centered coverage by several instruments
  - CTX will automatically support a HiRISE-driven target
- Certain observations can only be acquired during specific time periods
  - Stereo completion requests
  - CRISM IR requests
- HiRISE targets submitted via HiWish
  - Open to public and scientists alike
  - <http://www.uahirise.org/hiwish/>
  - Can browse suggestions or acquired images



# Landing Site Selection

## Example of Science Planning on MRO via HiWish

- Once target is submitted via HiWish, HiRISE Science Theme Leads (STLs) look at requests and prioritize based on the science rationale
- Science team members (CIPPs) plan the images
- Targeting Specialists (HiTS) examine details and plan observations
- A suggestion is “retired” if it has been planned into the ITL via the MRO Science Planning process
- HiRISE observes the target and MRO transmits the raw image data to Earth
- Automated processes convert the data to image products
- HiRISE staff looks at the data to determine if the product is usable
  - If not, the original suggestion “unretired” and fed back into science planning loop
  - If usable, images are released to public with PDS release, sometimes sooner in the online image catalog



# MRO Science Planning

## Summary

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- Science Planning is the integration of various science, relay, and engineering activities
- Relay and science are all planned in the same science planning process on MRO
- Various challenges in science planning based on ground or S/C configuration; many met through constraints and allocations
- Takes several weeks to plan request and acquire
- Takes weeks – years from original request in system based on type and priority of data requested!

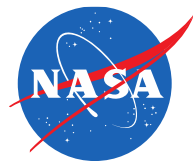




*Questions?*

Thank you!





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Backup

# MRO Science Investigations

<i>Instrument</i>	<i>Type</i>	<i>PI/TL, Institution</i>	<i>Attributes</i>
<b>CRISM</b>	Hyper-Spectral Imaging VIS-NIR Spectrometers	<i>Scott Murchie, PI</i> APL / Johns Hopkins University	Targeted Observing @ 18 m/pixel Regional Survey @ 100-200 m/pixel Very High Data Rate 85% of Mars surveyed in 544 channels
<b>HiRISE</b>	Very High Resolution Imaging	<i>Alfred McEwen, PI</i> University of Arizona	Targeted Imaging @ 30 cm/pixel Swath: 5.4 km w. 1.2 km 3-color strip Very High Data Rate / 2.7% of Mars
<b>SHARAD</b>	Shallow Subsurface RADAR (Provided by ASI)	<i>Roberto Seu, TL/PI</i> University of Rome <i>Roger Phillips, rDTL</i> <i>Nathaniel Putzig, aDTL</i>	Regional Radar Profiling of Subsurface Profiles to 0.5 km in regolith / 1.5 km in ice @ ~10 m vertical resolution High Data Rate
<b>CTX</b>	High-Resolution Context Imager	<i>Michael Malin, TL</i> Malin Space Science Systems	Targeted & Regional Survey 6 m/pixel, panchromatic in 30 km swath High Data Rate / 98% of Mars
<b>MARCI</b>	Mars Color Imager	<i>Michael Malin, PI</i> Malin Space Science Systems	Daily Global Mapping ~1 km/pixel in 7 color bands Moderate Data Rate / > 5.4 Mars yrs.
<b>MCS</b>	Mars Climate Sounder	<i>Daniel McCleese, PI</i> JPL / Caltech	Daily Global Sounding (T, p, aerosols) ~5 to 80 km Low-Data Rate / > 5.4 Mars yrs.
<b>ACCEL</b>	Facility Science Team Investigation	<i>Gerald Keating*, TL</i> GWU / LaRC	Profiled upper atmosphere using S/C Accelerometers during Aerobraking. (complete)
<b>Gravity Science</b>	Facility Science Team Investigation	<i>Maria Zuber, TL</i> MIT / GSFC	Data from DSN tracking using Spacecraft X Band Telecom

